

# Day 2

**beyond cloud cover**

**summary and issues**

# cloud data and “offerings”

- **optical depth (solar)**
  - Polder, Calipso (thin), MODIS-CE, ATSR, ISCCP, MODIS-ST, PATMOS
- **optical depth (IR) or emissivity**
  - Calipso, HIRS, AIRS/TOVS
- **particle size (water)**
  - MODIS-CE, ATSR, ISCCP, MODIS-ST, PATMOS
- **particle size (ice)**
  - MODIS-CE, Calipso, ISCCP, AIRS/TOVS, MODIS-ST, PATMOS
- **cloud phase**
  - Polder, Calipso
- **liquid water content**
  - MODIS-CE, ATSR, PATMOS
- **ice water content**
  - Calipso, ATSR, ISCCP, AIRS/TOVS
- **profile**
  - Calipso, ATSR, ISCCP

**many products  
to choose from**

# and now ?

- **The good**
  - many choices, complementary in nature
- **The bad**
  - sparse and biased sample, limited detection range, uncertainties often poorly defined
- **The ugly**
  - data-statistics is applied (often un-educated) to “validate” or evaluate modeling

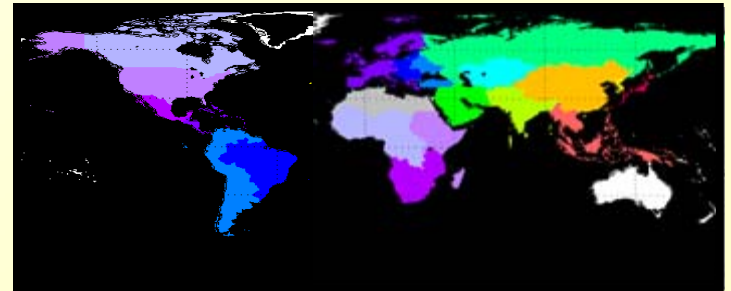
# needs

## ○ **assessment report**

- **summarize, what each product can do (best)**
- **stratify temporally (seasonally, daily)**
- **stratify spatially (zonally, regionally)**

## ○ **recommendations (?), yes !**

- **how and when to use**
- **synergies**



# compare cloud data products (1)

## many cloud retrievals are ill-defined

- what is a cloud (depends on the part of the spectrum as well as the application)? What is the function of a cloud mask (for what user community/science purpose)?
- what is the cloud-top height (radar vs. lidar vs. IR vs. polarization vs. molecular absorption vs. Raman scattering line filling)?
- cloud phase? for which layer(s)? Mixed phase?
- cloud effective particle size ? at what level ?, local quantity, not vertically integrated as with  $t$

# compare cloud data products (2)

**what model assumptions (e.g., ice cloud models) are used?**

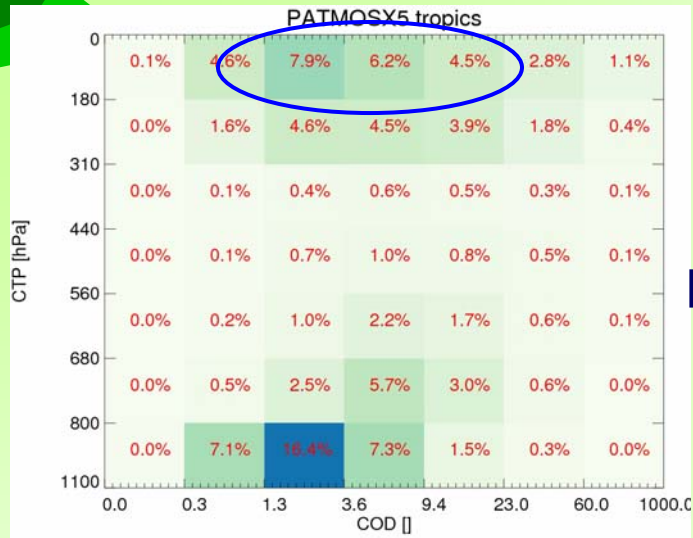
**what ancillary data sets are used?**

**what QA (Quality Assessment), uncertainties, or other choices are made to screen or weight retrievals ?**

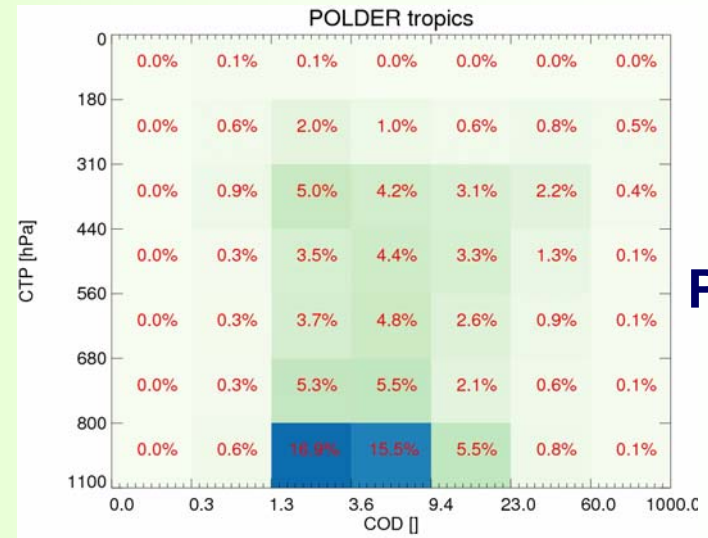
**no instrument covers the entire PDF**

**each technique/algorithm has a particular part of the solution space for which it is “useful”**

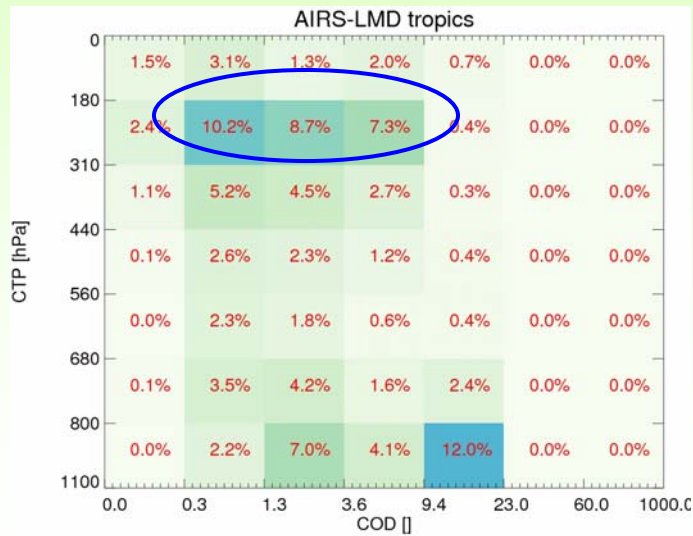
# COD-CP histograms: Tropics (30S – 30N)



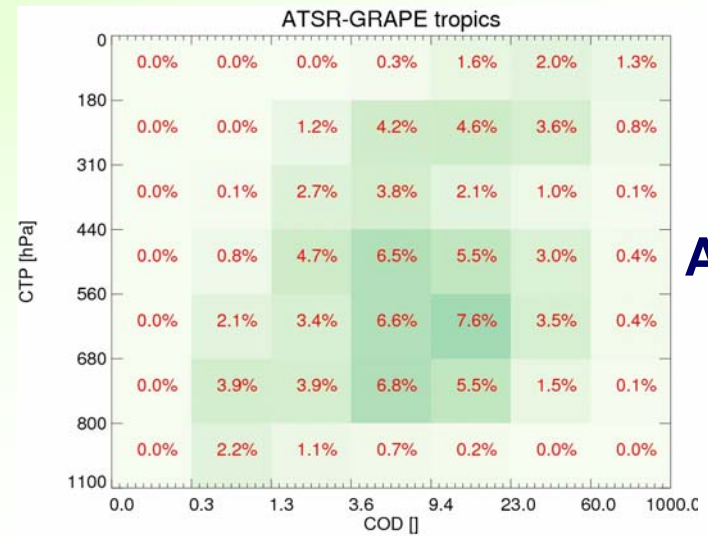
**PATMOS**



**POLDER**



**AIRS**



**ATSR**

# some issues (1)

## ○ **sampling**

- temporal and spatial ... often sparse, and QA data are often biased

## ○ **identify sweet-spots**

- retrievals are best in ranges (vary by sensor) ... so uncertainty histograms are desirable

## ○ **limitations**

- retrievals of upper and lower bound ... how do missed data impact

## ○ **dependencies**

- some properties are at the end of the food-chain → larger uncertainties (e.g. ice habit impact)



## some issues (2)

- **focus on uncertainties (that matter to user)**
- **no microwave data-set in the data-base**
- **linking solar and IR opt.depth**
- **understanding the low opt.depth detection**
  - **... to be able to link cloud cover data**

# a global modeler's perspective (1)

- evaluation of vertically distributed water
- evaluation of (L)WC → heating rate profiles
- **Qs**
  - are the simulated properties (spatially highly averaged ~ 100\*100km) in the right ball-park ?
    - upper and lower bound statistics needed
    - spatially and regionally stratified ... if possible
  - water content (high values missed ?)
  - total optical depth (how to average ?)
  - radiative fluxes (simulator?)
  - particle size
  - vertical distribution and phase partitioning

# a global modeler's perspective (2)

- given the variety of products offered...  
... explaining differences (strength and deficiencies) are not good enough
- uncertainty ranges are essential ...  
... otherwise best estimates are taken as “data-truth”
- model-simulators are not always the answer